

## Lecture 2

# Epidemiology with Uncertainty: Response to Bio-Terror

Yakov Ben-Haim

Technion

Israel Institute of Technology



# Contents

- 1 Response to Bio-Terror (bio-terror02.tex) **3****

  - 1.1 Simplified Epidemiological Model . . . . . 7**
  - 1.2 Info-Gap Model of Uncertainty . . . . . 10**
  - 1.3 Decisions and Their and Robustness . . . . . 15**
  - 1.4 Properties of the Robustness Function . . . . . 25**
  - 1.5 Preference Reversal and the Innovation Dilemma . . . . . 31**
  - 1.6 Summary . . . . . 41**

  
- 2 Conclusion (paris2023Lec02-001.tex) **47****

# 1 *Response to Bio-Terror*

## § Analysis and planning:

Use models and data to ameliorate impact of bio-terror attack.

§

## § Analysis and planning:

Use models and data to ameliorate impact of bio-terror attack.

## § The challenge: Info-gaps.

- Event scenario.
- Mass psychology.
- Epidemiological complexity.
-

## § Analysis and planning:

Use models and data to ameliorate impact of bio-terror attack.

## § The challenge: Info-gaps.

- Event scenario.
- Mass psychology.
- Epidemiological complexity.
- Model error and incompleteness:
  - Structure.
  - Parameters.
- Data error.
- Numerical and analytical approximations.

## 1.1 *Simplified Epidemiological Model*

## § Simplified epidemiological Model:

$$\frac{dS(t)}{dt} = -\gamma S(t)I(t)$$

$$\frac{dI(t)}{dt} = \gamma S(t)I(t) - \rho I(t)$$

$S(t)$  = Number of susceptibles.

$I(t)$  = Number of infected.

$\gamma$  = constant infection rate.

$\rho$  = constant removal rate.

**Removal:** death or recovery.

## § Approximate solution:

$$S(t) = S_0 + ge^{-\mu t}$$

$$I(t) = I(0)e^{-\rho t} + \frac{g\mu}{\rho - \mu} (e^{-\mu t} - e^{-\rho t})$$

$S_0 + g$  = initial susceptible population.

$S_0$  = final susceptible population.

$\mu$  = approximate infection rate.

## § Total number of deaths:

$$N = \int_0^{\infty} D\rho I(t) dt$$

$$\approx [I(0) + g]D$$

$D$  = fraction of “removed” who die.

## 1.2 *Info-Gap Model of Uncertainty*

## § Uncertainties:

- Analytical simplifications.
- Modelling errors: Info-gaps.

§

## § Uncertainties:

- Analytical simplifications.
- Modelling errors: Info-gaps.

## § Specifically:

$\tilde{S}(t)$  = known approx. susceptible pop.

$S(t)$  = unknown true susceptible pop.

$$\left| \frac{S(t) - \tilde{S}(t)}{\tilde{S}(t)} \right| = \text{Unknown fractional error} \quad (1)$$

## § Info-gap model, unknown fractional error:

$$\mathcal{U}(h, \tilde{S}(t)) = \left\{ S(t) : \left| \frac{S(t) - \tilde{S}(t)}{\tilde{S}(t)} \right| \leq h \right\}, \quad h \geq 0 \quad (2)$$

- Unknown  $S(t)$  at uncertainty  $h$ .
- Unknown horizon of uncertainty  $h$ .

§

## § Info-gap model, unknown fractional error:

$$\mathcal{U}(h, \tilde{S}(t)) = \left\{ S(t) : \left| \frac{S(t) - \tilde{S}(t)}{\tilde{S}(t)} \right| \leq h \right\}, \quad h \geq 0 \quad (3)$$

- Unknown  $S(t)$  at uncertainty  $h$ .
- Unknown horizon of uncertainty  $h$ .

## § Info-gap model:

- Unbounded uncertainty:  $h \geq 0$ .
- No worst case.
- Not min-max analysis.

### 1.3 *Decisions and Their and Robustness*

## § Decisions:

- Vaccinations: public and professionals.
  - Mass vaccinate.
  - Trace and vaccinate.
- Quarantine.
- Surveillance.
- Travel restrictions.
- Etc.

## § Decisions influence:

- $\mu =$  infection rate.
- $\rho =$  removal rate (death or recovery).
- $g =$  additional number of infected.
- $I(0) =$  initial number of infected.
- $D =$  fraction of “removed” who die.
- Etc.

§  $q =$  **decision vector**: policy.

§ **Policy goal:**

$$\text{Mortality} \leq N_c.$$

§

## § Policy goal:

$$\text{Mortality} \leq N_c.$$

## § Mortality with policy $q$ :

- **Known estimated:**  $N(q, \tilde{S})$ .
- **Unknown actual:**  $N(q, S)$ .

§

## § Policy goal:

$$\text{Mortality} \leq N_c.$$

## § Mortality with policy $q$ :

- **Known estimated:**  $N(q, \tilde{S})$ .
- **Unknown actual:**  $N(q, S)$ .

## § **Unknown** horizon of uncertainty $h$ .

§

## § Policy goal:

$$\text{Mortality} \leq N_c.$$

## § Mortality with policy $q$ :

- **Known estimated:**  $N(q, \tilde{S})$ .
- **Unknown actual:**  $N(q, S)$ .

## § **Unknown** horizon of uncertainty $h$ .

## § **Robustness** of policy $q$ :

Max error,  $h$ , at which

**policy goal** guaranteed:  $N(q, S) \leq N_c$ .

§ **Robustness** of policy  $q$ :

Max error,  $h$ , at which

**policy goal** guaranteed:  $N(q, S) \leq N_c$ .

§

§ **Robustness** of policy  $q$ :

Max error,  $h$ , at which

**policy goal** guaranteed:  $N(q, S) \leq N_c$ .

§ **Robust-satisficing strategy**:

- **Satisfice** policy goal.
- **maximize** robustness.

§

## § Robustness of policy $q$ :

Max error,  $h$ , at which

policy goal guaranteed:  $N(q, S) \leq N_c$ .

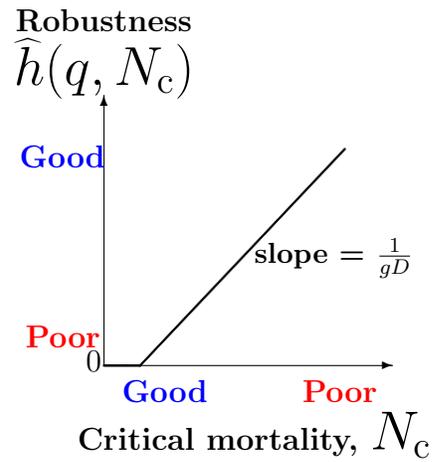
## § Robust-satisficing strategy:

- Satisfice policy goal.
- maximize robustness.

## § Robustness:

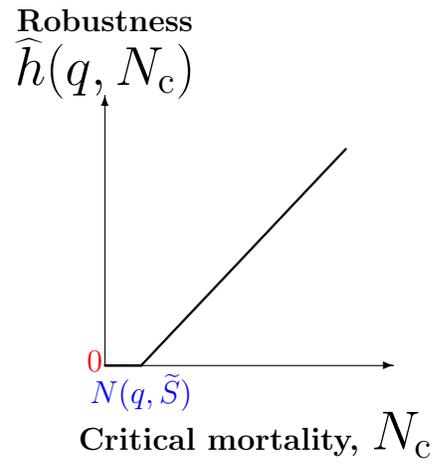
$$\hat{h}(q, N_c) = \max \left\{ h : \left( \max_{S \in \mathcal{U}(h, \tilde{S})} N(q, S) \right) \leq N_c \right\} \quad (4)$$

## 1.4 *Properties of the Robustness Function*



§ Trade-off: robustness up, performance down.

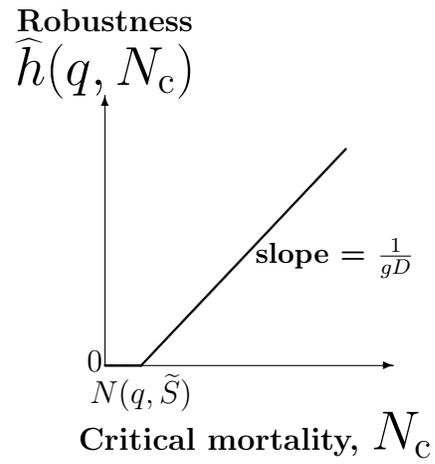
$$\widehat{h}(q, N_c) = \begin{cases} \frac{1}{gD}[N_c - N(q, \tilde{s})] & \text{if } N(q, \tilde{s}) \leq N_c \\ 0 & \text{else} \end{cases} \quad (5)$$



## § Zeroing:

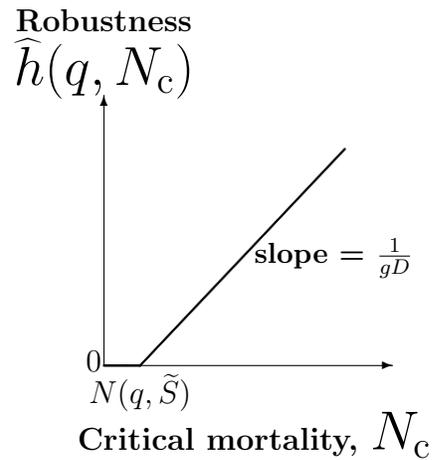
no robustness of estimated performance:

$$\hat{h}(q, N_c) = 0 \quad \mathbf{if} \quad N_c = N(q, \tilde{S}) \quad (6)$$



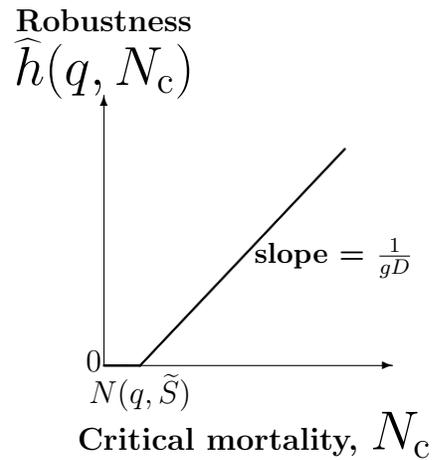
## § What does robustness mean?

- $\widehat{h}(q, N_c) = 0.1$ : robust to 10% error in  $\widetilde{S}$ .
-



## § What does robustness mean?

- $\widehat{h}(q, N_c) = 0.1$ : robust to 10% error in  $\widetilde{S}$ .
- Slope =  $1/gD \approx 1/(1000 \times 0.3) = 1/300$
- $g = \#$  infected.  $D =$  fraction of deaths.
-



## § What does robustness mean?

- $\hat{h}(q, N_c) = 0.1$ : **robust to 10% error in  $\tilde{S}$ .**
- **Slope** =  $1/gD \approx 1/(1000 \times 0.3) = 1/300$
- $g$  = # infected.  $D$  = fraction of deaths.
- $N_c$  up by **30**:  $\hat{h}(q, N_c)$  up by **0.1**
- **50% robustness**:  $N_c = N(q, \tilde{S}) + 0.5 \times 300$ .

## 1.5 *Preference Reversal and the Innovation Dilemma*

## § Two policies, $q$ and $q^\bullet$ :

- $q$ :  $\rho, I(0), g, D$ . **Innovative, hi-tech, less familiar.**
-

## § Two policies, $q$ and $q^\bullet$ :

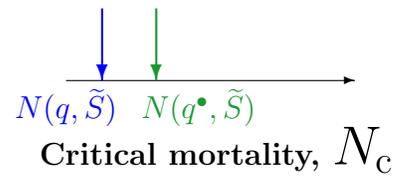
- $q$ :  $\rho$ ,  $I(0)$ ,  $g$ ,  $D$ . **Innovative, hi-tech, less familiar.**
- $q^\bullet$ :  $\rho^\bullet$ ,  $I^\bullet(0)$ ,  $g^\bullet$ ,  $D^\bullet$ . **State of the art, more familiar.**

§

## § Two policies, $q$ and $q^\bullet$ :

- $q$ :  $\rho, I(0), g, D$ . **Innovative, hi-tech, less familiar.**
- $q^\bullet$ :  $\rho^\bullet, I^\bullet(0), g^\bullet, D^\bullet$ . **State of the art, more familiar.**

## § Decision dilemma: which to choose?

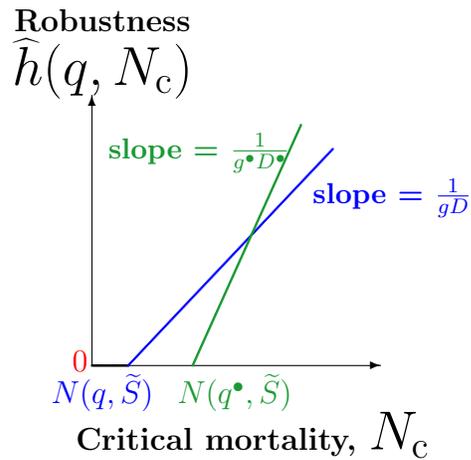


§ **Nominal preference:**

$$N(q, \tilde{S}) < N(q^\bullet, \tilde{S}) \quad (7)$$

implies nominal preference for innovative policy:

$$q \succ q^\bullet \quad (8)$$



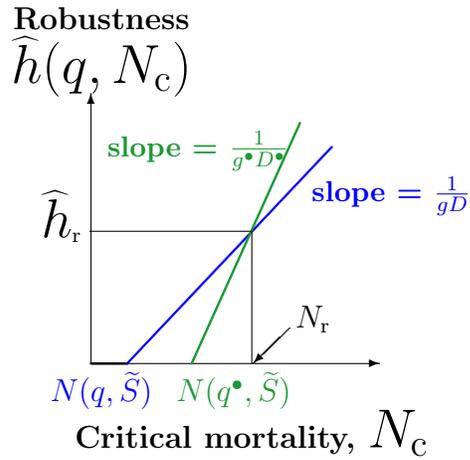
§ Nominal preference for innovative policy

$$q \succ q^\bullet \tag{9}$$

has **zero robustness:**

$$\widehat{h}(q, N_c) = 0 \quad \text{if} \quad N_c = N(q, \tilde{S}) \tag{10}$$

and **higher cost of robustness:** lower slope.

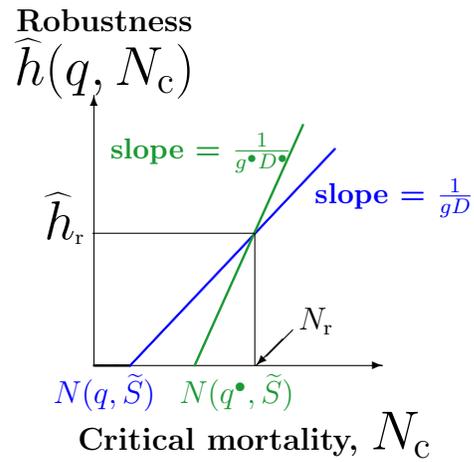


§ Nominal preference:  $q \succ q^*$ .

§ Preference reversal: innovation dilemma resolved.

- If  $N_c > N_r$  adequate, then  $q^* \succ q$ .

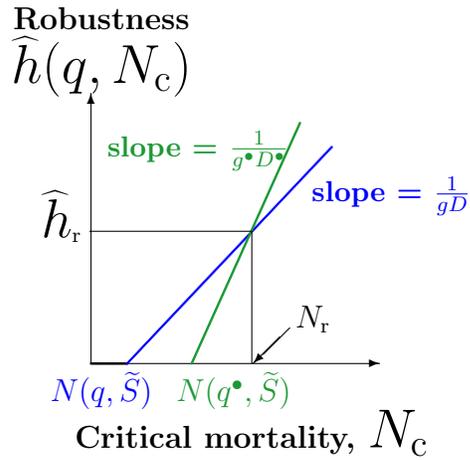
-



§ Nominal preference:  $q \succ q^*$ .

§ Preference reversal: innovation dilemma resolved.

- If  $N_c > N_r$  adequate, then  $q^* \succ q$ .
- If  $N_c < N_r$  required, then  $q \succ q^*$ .

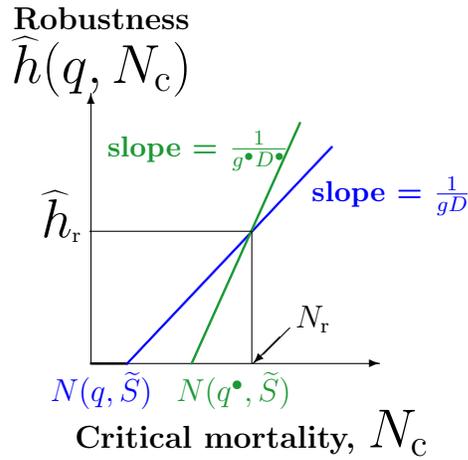


§ Example.

| Parameter             | Design $q$ | Design $q^*$ |
|-----------------------|------------|--------------|
| $\rho$                | 0.05       | 0.06         |
| $I(0)$                | 1000       | 1300         |
| $g$                   | 1000       | 800          |
| $N(q, \widetilde{S})$ | 600        | 630          |
| $1/(gD)$              | 0.00333    | 0.00417      |

§ Nominal preference:

$$N(q, \widetilde{S}) = 600 < 630 = N(q^*, \widetilde{S}) \quad \text{so} \quad q \succ q^* \quad (11)$$



§ Nominal preference:

$$N(q, \widetilde{S}) = 600 < 630 = N(q^\bullet, \widetilde{S}) \quad \text{so } q \succ q^\bullet \quad (12)$$

§ Curves cross: slope  $>$  slope

If  $\widehat{h}_r = 0.5$ ,  $N_r = 750$  adequate, then  $q^\bullet \succ q$

## 1.6 *Summary*

§ Use **models to choose policy.**

§

§ Use **models to choose policy.**

§ **Models err:** info-gaps.

Hence: **require robustness.**

§

§ Use **models to choose policy.**

§ **Models err:** info-gaps.

Hence: **require robustness.**

§ **Nominal predictions: zero robustness.**

§

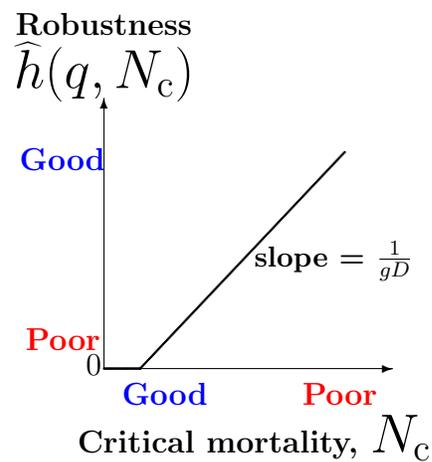
§ Use models to choose policy.

§ Models err: info-gaps.

Hence: require robustness.

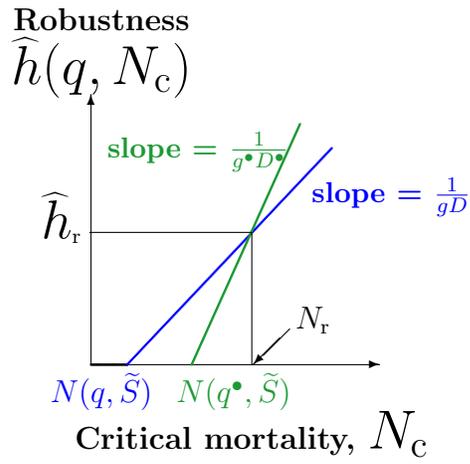
§ Nominal predictions: zero robustness.

§ Robustness trades-off against performance.



# § Robustness curves may cross:

Preference reversal: innovation dilemma resolved.



## **2** *Conclusion*

## In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§

## In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§ Info-gap uncertainty is unbounded.

§

## In Conclusion

§ **Info-gap uncertainty:**

innovation, discovery, ignorance, surprise.

§ **Info-gap uncertainty is unbounded.**

§ **Optimism:** our models get better all the time.

§

## In Conclusion

§ **Info-gap uncertainty:**

innovation, discovery, ignorance, surprise.

§ **Info-gap uncertainty is unbounded.**

§ **Optimism:** our models get better all the time.

§ **Realism:** our models are wrong now  
(and we don't know where or how much).

§

## In Conclusion

### § Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

### § Info-gap uncertainty is unbounded.

### § Optimism: our models get better all the time.

### § Realism: our models are wrong now

(and we don't know where or how much).

### § Responsible decision making:

- Specify your goals.
- Maximize your robustness to uncertainty.
- Study the trade offs.
- Exploit windfall opportunities.